## KEY FEATURES

- LOW COST
- HIGH VOLTAGE - 200 VOLTS
- HIGH CURRENT - 10 AMPS
- 125 WATT DISSIPATION CAPABILITY
- 100kHz POWER BANDWIDTH
- SHORT CIRCUIT PROTECTION
- TEMPERATURE MONITORING
- RoHS COMPLIANT
- CONFORMALLY COATED

APPLICATIONS

- INKJET PRINTER HEAD DRIVE
- PIEZO TRANSDUCER DRIVE
- INDUSTRIAL INSTRUMENTATION
- RELECTOMETERS
- ULTRA-SOUND TRANSDUCER DRIVE


## DESCRIPTION

The PAD148-1 is a high voltage operational amplifier constructed with surface mount components to provide a cost effective solution for many industrial applications With a footprint only $3.3 \mathrm{in}^{2}$ the PAD148-1 offers outstanding performance that rivals more expensive hybrid component amplifiers. User selectable external compensation tailors the amplifier's response to the application requirements. An analog output voltage is provided that is proportional to the substrate temperature. The amplifier's output stage is shut down by pulling the shut down pin low or when the substrate temperature exceeds $110^{\circ} \mathrm{C}$. A short circuit or over-current condition also shuts down the output stage. The amplifier circuitry is built on a thermally conductive but electrically insulating substrate. No BeO is used in the PAD148-1. The resulting module is a small, high performance solution for many industrial
 applications. The PAD148-1 is a special version of the base product PAD148 where the fault sense voltage is 0.65 V and the output stage is biased class C to lower quiescent current.

## EQUIVALENT CIRCUIT



PINOUT \& CONNECTIONS


# ABSOLUTE MAXIMUM RATINGS SPECIFICATIONS 

|  | ABSOLUTE MAXIMUM RATINGS |  |  |
| :--- | :--- | :--- | ---: |
| SUPPLY VOLTAGE, +Vs to -Vs | 200 V | TEMPERATURE, pin solder, 10 s | 237 C |
| BOOST VOLTAGE, | $\pm \mathrm{V}_{\mathrm{B}} \pm 20 \mathrm{~V}$ | TEMPERATURE, junction${ }^{2}$ | $150^{\circ} \mathrm{C}$ |
| OUTPUT CURRENT, within SOA | 12 A | TEMPERATURE RANGE, storage | -40 to $105^{\circ} \mathrm{C}$ |
| POWER DISSIPATION, internal, DC | 125 W | OPERATING TEMPERATURE, case | -40 to $105^{\circ} \mathrm{C}$ |
| INPUT VOLTAGE, differential | $\pm 20 \mathrm{~V}$ |  |  |
| INPUT VOLTAGE, common mode | $\pm \mathrm{V}_{\mathrm{B}}$ |  |  |


| PARAMETER | TEST CONDITIONS ${ }^{1}$ | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| INPUT |  |  |  |  |  |
| OFFSET VOLTAGE |  |  | 1 | 3 | mV |
| OFFSET VOLTAGE vs. temperature | Full temperature range |  | 20 | 50 | $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$ |
| OFFSET VOLTAGE vs. supply |  |  |  | 20 | $\mu \mathrm{V} / \mathrm{V}$ |
| BIAS CURRENT, initial ${ }^{3}$ |  |  |  | 100 | pA |
| BIAS CURRENT vs. supply |  |  |  | 0.1 | pA/V |
| OFFSET CURRENT, initial |  |  |  | 50 | pA |
| INPUT RESISTANCE, DC |  |  | 100 |  | G $\Omega$ |
| INPUT CAPACITANCE |  |  | 4 |  | pF |
| COMMON MODE VOLTAGE RANGE |  |  |  | $+\mathrm{V}_{\mathrm{B}}-12$ | V |
| COMMON MODE VOLTAGE RANGE |  |  |  | $-\mathrm{V}_{\mathrm{B}}+7$ | V |
| COMMON MODE REJECTION, DC |  | 98 | 106 |  | dB |
| NOISE | 100 kHz bandwidth, $1 \mathrm{k} \Omega \mathrm{R}_{\mathrm{S}}$ |  | 10 |  | $\mu \mathrm{V}$ RMS |
| FAULT SENSING INPUTS |  |  |  |  |  |
| R (RESET), $10 \mu \mathrm{~S}$ min pulse width | Relative to GND, $>4.5 \mathrm{~V}$ to insure reset | 0 |  | 5.5 | V |
| +F |  | -Vs |  | +Vs | V |
| -F |  | -Vs |  | +Vs | V |
| +F TO -F | Differential voltage, shutdown |  | $\pm 0.65$ |  | V |
| $\overline{S D}$ | $<0.2 \mathrm{~V}$ to insure shutdown | 0 |  | 5.5 | V |
| GAIN |  |  |  |  |  |
| OPEN LOOP | $\mathrm{R}_{\mathrm{L}}=10 \mathrm{k} \Omega, \mathrm{C}_{\mathrm{C}}=10 \mathrm{pF}$ | 108 |  |  | dB |
| GAIN BANDWIDTH PRODUCT @ 1MHz | $\mathrm{C}_{\mathrm{C}}=10 \mathrm{pF}$ |  | 10 |  | MHz |
| PHASE MARGIN | Full temperature range | 45 | 60 |  | degree |
| OUTPUT |  |  |  |  |  |
| VOLTAGE SWING | $\mathrm{I}_{\mathrm{O}}=10 \mathrm{~A}$ | $\pm$ Vs-10 | +Vs-8.6 |  | V |
| VOLTAGE SWING | $\mathrm{I}_{\mathrm{O}}=-10 \mathrm{~A}$ | -Vs+10 | -Vs+7 |  | V |
| VOLTAGE SWING | $+\mathrm{V}_{\mathrm{B}}=+\mathrm{Vs}+10 \mathrm{~V}, \mathrm{I}_{\mathrm{O}}=10 \mathrm{~A}$ | +Vs-1.6 | +Vs-1.2 |  |  |
| VOLTAGE SWING | $-V_{B}=-\mathrm{Vs}-10 \mathrm{~V}, \mathrm{I}_{0}=-10 \mathrm{~A}$ | -Vs-5.1 | +Vs+4.1 |  |  |
| CURRENT, continuous, DC |  | 10 |  |  | A |
| SLEW RATE, $\mathrm{A}_{\mathrm{V}}=-10$ | $\mathrm{C}_{\mathrm{C}}=10 \mathrm{pF}$ | 65 | 85 |  | V/ $/ \mathrm{S}$ |
| SETTLING TIME, to 0.1\% | 2 V Step, $\mathrm{C}_{\mathrm{C}}=10 \mathrm{pF}$ |  | 1 |  | $\mu \mathrm{S}$ |
| RESISTANCE | No load, DC |  | 4 |  | $\Omega$ |
| POWER BANDWIDTH, 180 Vp -p | $\mathrm{C}_{\mathrm{C}}=10 \mathrm{pF}$ |  | 150 |  | kHz |
| POWER SUPPLY |  |  |  |  |  |
| VOLTAGE |  | $\pm 15$ | $\pm 75$ | $\pm 100$ | V |
| CURRENT, quiescent |  |  | 21 | 25 | mA |
| THERMAL |  |  |  |  |  |
| RESISTANCE, AC, junction to case ${ }^{5}$ | Full temperature range, $\mathrm{f} \geq 60 \mathrm{~Hz}$ |  |  | 0.8 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| RESISTANCE, DC junction to case | Full temperature range |  |  | 1.0 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| RESISTANCE, DC junction to air | Full temperature range |  |  | 13 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| TEMPERATURE RANGE, case |  | -40 |  | 105 | ${ }^{\circ} \mathrm{C}$ |

## NOTES:

1. Unless otherwise noted: $T_{C}=25^{\circ} C$, compensation $C c=100 \mathrm{pF}, \mathrm{DC}$ input specifications are $\pm$ value given, power supply voltage is typical rating.
2. Derate internal power dissipation to achieve high MTBF.
3. Doubles for every $10^{\circ} \mathrm{C}$ of case temperature increase.
4.     + Vs and $-V$ s denote the positive and negative supply voltages to the output stage. $+V_{B}$ and $-V_{B}$ denote the positive and negative supply voltages to the input stages.
5. Rating applies if the output current alternates between both output transistors at a rate faster than 60 Hz .
6. Power supply voltages $+V_{B}$ and $-V_{B}$ must not be less than $+V s$ and $-V s$ respectively. Total voltage $+V_{B}$ to $-V_{B} \mathbf{2 4 0 V}$ maximum.
7. The PAD148-1 is constructed with MOSFET transistors and ESD handling procedures must be observed.

## SAFETY FIRST

The operating voltages of the PAD148-1 are potentially deadly. When developing an application circuit it is wise to begin with power supply voltages as low as possible while checking for circuit functionality. Increase supply voltages slowly as confidence in the application circuit increases. Always use a "hands off" method whereby test equipment probes are attached only when power is off.

## OVER-CURRENT FAULT PROTECTION

The output stage of the PAD148-1 is shut down when an over-current fault is detected. The protection circuit monitors the voltage across an external sense resistor, Rs. The fault condition set point is programmed by:

$$
I_{F}=\frac{0.65 \mathrm{~V}}{R_{s}}
$$

## Where $I_{F}$ is the value of the fault current set point and $\mathbf{R}_{S}$

 is the value of the sense resistor.Whenever the programmed current set point is exceeded for more than $10 \mu \mathrm{~S}$ (typical) the drive to the output stage turns off completely (typically in less than $400 \mu \mathrm{~S}$ ), and remains off until the circuit is reset (pin $10, \mathrm{R}$ ) via a 5 V momentary pulse $\geq$ $10 \mu \mathrm{~S}$ (or power recycled). The internal sense voltage is a precision temperature compensated reference voltage of 0.65 V . The accuracy of the current fault sensing is typically better than $2 \%$, plus the tolerance of the external sense resistor. A Kelvin sense resistor is recommended for best accuracy. For some loads a start-up current may exceed the normal programmed maximum value. This condition should be considered when setting the programmed fault value. See Figure 1, below, for a typical over-current fault connection diagram.


Figure 1

## MOUNTING THE AMPLIFIER

In most applications the amplifier must be attached to a heat sink. Spread a thin and even coat of heat sink grease across the back of the PAD148-1 and also the heat sink where the amplifier is to be mounted. Push the amplifier into the heat sink grease on the heat sink while slightly twisting the amplifier back and forth a few times to bed the amplifier into the heat sink grease. On the final twist align the mounting holes
of the amplifier with the mounting holes in the heat sink and finish the mounting using 4-40 hex male-female spacers. Mount the amplifier to the mother board with 4-40 X 1/4" screws.

## PHASE COMPENSATION

The PAD148-1 must be phase compensated. The compensation capacitor, $\mathrm{C}_{\mathrm{C}}$, is connected between pins 5 and 6 . The compensation capacitor must be an NPO type capacitor rated for the full supply voltage ( 200 V ). On page 2, under Amplifier Pinout and Connections, you will find a table that gives recommended compensation capacitance value for various circuit gains and the resulting slew rate for each capacitor value. Consult also the small signal response and phase response plots for the selected compensation value in the Typical Performance Graphs section. Do not use a compensation capacitor less than 10 pF .

## BOOST OPERATION

The small signal stages of the PAD148-1 are connected to the $\pm V_{B}$ power supply pins. When the $\pm V_{B}$ voltages are greater than the $\pm \mathrm{Vs}$ power supply pins the small signal stages of the amplifier are biased so that the output transistors can be driven very close to the $\pm$ Vs rails. Close swings to the supply rails increase the efficiency of the amplifier and make better use the supply voltages. This technique is often used to operate the amplifier with only a single high current power supply, thus reducing the system size and cost. Also see the application article AN-22 Single Supply Operation with Power Op Amps for more detailed information and circuits.

## TEMPERATURE REPORTING

An analog output voltage is provided (pin 7, TMP) relative to ground (PIN 3) and proportional to the temperature in degrees $C$. The slope is approximately $-10.82 \mathrm{mV} /{ }^{\circ} \mathrm{C}$. The output voltage follows the equation:

$$
\begin{gathered}
\mathrm{T}=(2.127-\mathrm{V})(92.42) \\
\text { or } \\
\mathrm{V}=2.127-(\mathrm{T} / 92.42)
\end{gathered}
$$

Where V is the TMP output voltage and T is the substrate temperature in degrees C .

## THERMAL SHUTDOWN

The temperature monitoring circuit automatically turns off the output transistors when the substrate temperature reaches $110^{\circ} \mathrm{C}$. The output remains disabled until the substrate temperature falls below $100{ }^{\circ} \mathrm{C}$ and the circuit is reset ( R , pin 10). The thermal shutdown feature is activated by amplifier thermal overload such as sustained high power dissipation or inadequate heat sinking.

## EXTERNAL SHUTDOWN

When pin $9(\overline{S D})$ is taken low (GND) the output stage is turned off and remains off until reset at pin $10(\mathrm{R})$ with a 5 V pulse or power to the amplifier is restarted. If the $\overline{S D}$ pin is monitored with a high impedance circuit ( $>100 \mathrm{k}$ input impedance) it also gives an indication of the temperature status of the amplifier. A "high" ( +5 V ) indicates normal temperature operation and a "low" (zero volts, approximately) indicates that the amplifier is shut down due to the occurrence of an overtemp condition. See Figure 4 in Applications, page 10, for external shutdown circuits.

## POWER-UP CONDITIONS

In most applications the PAD148-1 is powered by two power supplies. Under normal conditions both power supply voltages start to ramp up to their final values at the same time. However, if one power supply starts well before the other the over-current protection circuit may keep the output stage turned off. In this case it will be necessary to apply a momentary 5 V reset pulse to pin 10 (Reset) to unlock the output stage of the amplifier. A auto-reset circuit can be connected to pin 10 to ensure that the amplifier's output is active upon power up, although this is not necessary if the power supplies are started at the same time. The form of this circuit is shown in Figure 3, Applications, page 10 .

## CONFORMAL COATING

The PAD148-1 has a conformal coating to help protect against humidity and dirty environments. It is best that the circuit only be handled by the edges of the board to prevent disturbing the coating. The silicone conformal coat is Dow Corning 1-2577 and is applied in a thickness from 0.1 to 0.2 mm .








(HVPS) Condatas AG



HARMONIC DISTORTION



Pos. Pulse response, $\mathrm{G}=-10, \mathrm{C}_{\mathrm{C}}=100 \mathrm{pF}, 47 \mathrm{nF}$ load


Neg. Pulse response, $G=-10, C_{C}=100 \mathrm{pF}, 47 \mathrm{nF}$ load


20 kHz sine into $8 \Omega$ load, $\mathrm{G}=-10, \mathrm{C}_{\mathrm{C}}=100 \mathrm{pF}$


SAFE OPERATING AREA



OPEN COLLECTOR OR OPEN DRAIN LOGIC GATES CIRCUIT

Figure 4
External Shutdown Circuits


